FAS-GED: GPU-Accelerated Graph Edit Distance Computation.

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1) Motivation and Introduction

• Graph Edit Distance (GED): Measures the similarity of graphs by quantifying the minimum cost of edit operations (insertion, deletion, substitution) needed to transform one graph into another.

Given graphs
$$g_1 = (V_1, E_1, \alpha_1, \beta_1)$$
 and $g_2 = (V_2, E_2, \alpha_2, \beta_2)$, the
 $GED(g_1, g_2) = \min_{\{o_1, o_2, \dots, o_k\} \in \gamma(g_1, g_2)} \sum_{i=1}^k cost(o_i)$

3) Performance Evaluation

- Accuracy: FAS-GED achieves the optimal edit distance in over 90% of cases with a deviation less than 0.5% using synthetic graphs with varying sizes and densities.
- **Speedup**: Up to 55× speedup over NetworkX library [2] for small size graphs.



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- where $\gamma(g_1, g_2)$ denotes all possible edit paths.
- Applications: GED is used in fields like bioinformatics, computer vision, and pattern recognition, enabling tasks such as molecular structure comparison and image matching.
- **Challenge**: High complexity that increases exponentially with the size of graphs, making efficient GED computation crucial for large graphs.

Proposed Solution: FAS-GED

- Goal: Develop a Fast, Accurate, and Scalable approach for GED computation leveraging GPU architectures.
- Key Features:
 - High accuracy comparable to exact methods with significantly reduced computation time.
 - Efficient best-k elements retrieval on GPU to balance accuracy/scalability. A larger value of K prioritizes accuracy, while a smaller value of K enhances scalability.
 - Efficient utilization of GPU capabilities to handle large graphs with minimal host-device communication.

2) FAS-GED Methodology

FAS-GED explores the search tree level by level on GPUs and cuts off all nodes with a ranking greater than a given parameter (K) [1].

- Scalability: Support graph sizes up to 1000 vertices, with an excellent accuracycomplexity trade-off.
- Approximate results: Demonstrates robust performance diverse real-world across datasets compared to Beam Search (BS) and Depth First Search (DFS) state-of-the-art methods.



Figure 2: FAS-GED vs. NetworkX open source library.



Figure 3: FAS-GED compared to BS and DFS₁ results using real-world

datasets.

4) Optimization of FAS-GED

Hardware Optimization

 Improve the data layout for efficient memory access, up to 50% improvement over the nonoptimized version.



- Three-Phase GPU Process:
 - Branching Phase:
 - * Apply edit operations to expand the nodes at a given tree level.
 - * Efficiently leverage GPU parallelism for simultaneous node expansion and evaluation of the partial edit distance.

- Ranking Phase:

* Rank the expanded nodes using local and global ranking mechanisms within GPU blocks, exploiting atomic operations without host intervention.

- Update Phase:

* Update primary data structures with the best K nodes' data based on the ranking.

• Benefits:

- Reduces host-device communication, significantly improving performance.
- Scales efficiently with graph size in a linear complexity.



- FAS-GED achieves a 300× speedup over its baseline CPU version on a 48-core AMD Epyc CPU.
- Bottleneck: Synchronization overhead in top-k search, accounting for 80% of execution time and explaining performance of A100 to H100 GPUs.

Figure 4: FAS-GED Optimization and hardware scaling.

5) Application in Classification

- Enabling facst accurate GED measurement for K-Nearest Neighbor (KNN) classifier in graph space.
- KNN/FAS-GED reaches similar accuracy compared to sophisticated Graph Neural Network approaches (GNN_NDP [3] and GNN_MEWISPool [4]) on Mutagenicity dataset.



Figure 5: KNN/FAS-GED vs. GNN for Graph Classification.



6) Conclusions

- Summary: FAS-GED significantly advances GED computation by balancing speed, accuracy, and scalability on GPU architectures.
- **Future Work**: Focuses on optimization and extending the approach to very large graph sizes, while focusing on the application side.

References:

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